## **User's Manual**

For

### **ESS24-30**

#### **Integrated Stpper Motor**

©2020 All Rights ReservedAttention: Please read this manual carefully before using the Motor!



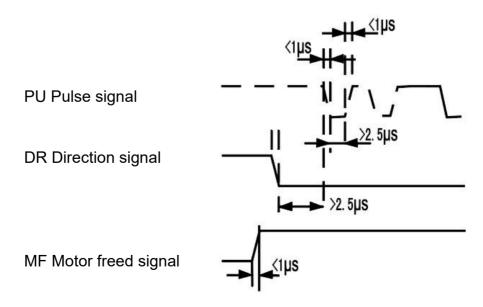
#### **ESS24-30**

### **Integrated Stepper Motor**

### **Features**

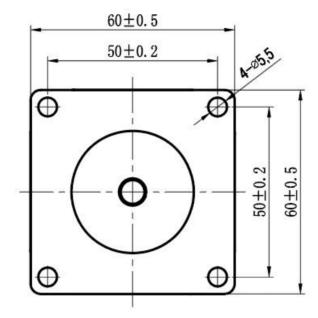
- Using a new 32-bit motor control, dedicated DSP chip
- Pulse input frequency up to 200 KHz
- Small torque attenuation, speed up to 3000 RPM
- Built-in alarm output, for monitoring and controlling
- Intelligently adjust current, reduce vibration, noise and this can increase efficiency by 35%
- Pulse/direction (PU/DR) control
- Voltage range: DC24V ~ 50V
- Over-voltage, under-voltage and over-current protection
- Excellent high speed performance and rigidity, combined with advantages of servo motor and stepper motor
- Drive and motor integrated, simple wiring

### Input signal waveform sequence diagram

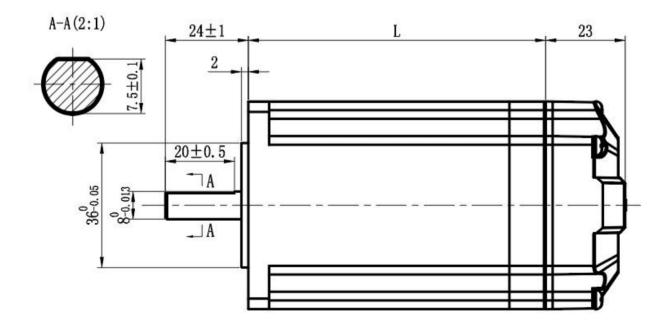


# Installation size (unit: mm)

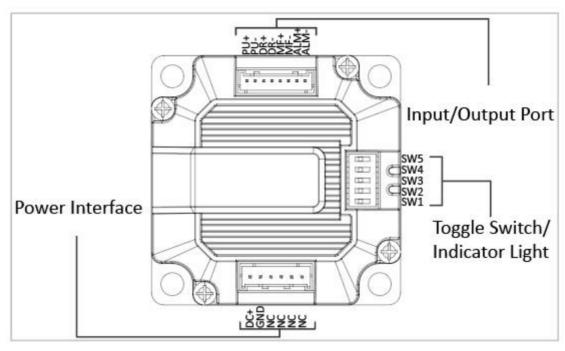
# Front view



# Side view



## **Input / Ouput ports**



Function	Specification	Remark
VDC+	Supply voltage	VDC: 24 ~ 50V
GND	Ground	
PU+	Pulse input signal+	
PU-	Pulse input signal-	Cierral manuar annuh u
DR+	Direction input signal+	Signal power supply: 5V ~ 24V, >5V, add a current-limiting resistance
DR-	Direction input signal-	>5V, add a current-inflitting resistance
MF+	Motor freed signal+	
MF-	Motor freed signal-	
ALM+	Alarm output signal+	Over-current, over-voltage, position following error
ALM-	Alarm output signal-	alarm output. The maximum driving current is 50mA
-	NC	NC

# **Toggle Switch description**

PU/Rev	SW2	SW3	SW4	SW5
400	ON	ON	ON	ON
800	OFF	ON	ON	ON
1600	ON	OFF	ON	ON
3200	OFF	OFF	ON	ON
6400	ON	ON	OFF	ON
12800	OFF	ON	OFF	ON
25600	ON	OFF	OFF	ON
51200	OFF	OFF	OFF	ON
1000	ON	ON	ON	OFF
2000	OFF	ON	ON	OFF
4000	ON	OFF	ON	OFF
5000	OFF	OFF	ON	OFF
8000	ON	ON	OFF	OFF
10000	OFF	ON	OFF	OFF
20000	ON	OFF	OFF	OFF
40000	OFF	OFF	OFF	OFF

SW1: Motor rotation direction OFF=CW, ON=CCW

## **Electrical Specifications**

Dovometeve	ESS24-30			
Parameters	MIN	TYP	MAX	UNIT
Output Current	1.8	-	4.0	Α
Input Voltage	24	36	50	Vdc
Logic Signal Current	7	10	16	mA
Logic Signal Voltage	-	5	24	V
Pulse Input Frequency	0	-	200	kHz
Isolation Resistance	100	-	-	ΜΩ

# **Others Specifications**

Parameters	UNIT	ESS24-30
NO. of Phase		2
Step Angle	۰	1.8
Motor length	mm	86
Holding Torque	N.m	3.0
Rated Current	А	5.0
Resistance/Phase	Ω	0.43
Inducatance/Phase	mH	2.0
Rotor Inertia	g.cm2	690
Insulation Class		В
Operating Temperature	°c	0 ~ 55
Weight	Kg	1.4

## **Fault diagnosis**

Fault code	Fault Information	RUN/ALM Output	Reset
Err1:0x01	Over-current / short circuit		Power down reset
Err2:0x02	Over-voltage		Lock machine /auto recoery
Err3:0x03	Under-voltage		Lock machine /auto recoery
Err5:0x05	position following error		Power down reset

## **Operating Environment**

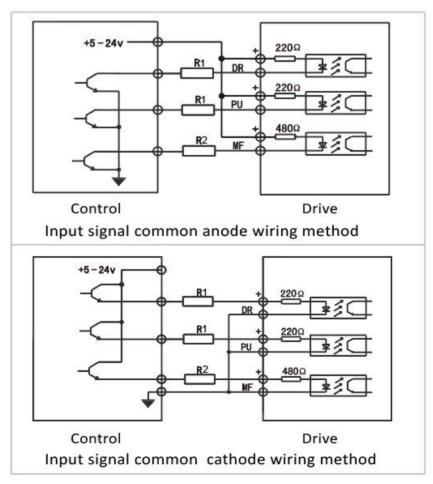
Cooling	Natural cooling		
	Workplace	Stay away from other heating sources, Avoid dust, oil fog , corrosive and combustible gases and Strong vibration site	
Working Environment	Temperature	0°c ~ 50°c	
	Humidity	40-90%RH(no condensation, no frosting)	
	Vibration	10 ~ 55Hz/0.15mm	
Storage Temperature	-20°c ~ +80°c		
Warning:  Motor installation, do not knock motor back cover, so as to avoid damage encoder.			

### **Control signal connection(Input singal)**

+5V: R1=0, R2=0

+12V: R1=510Ω, R2=820Ω

+24V:R1=1.2KΩ,R2=1.8KΩ



## **Control signal connection(Output singal)**

